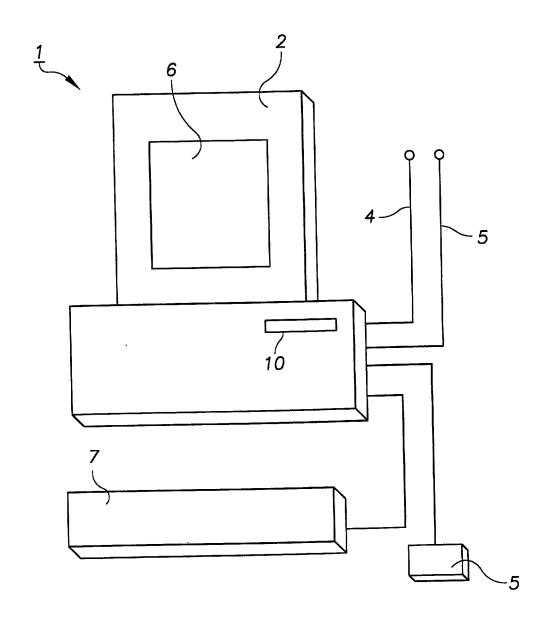
FIG.1



A STATE OF THE PARTY OF THE PAR

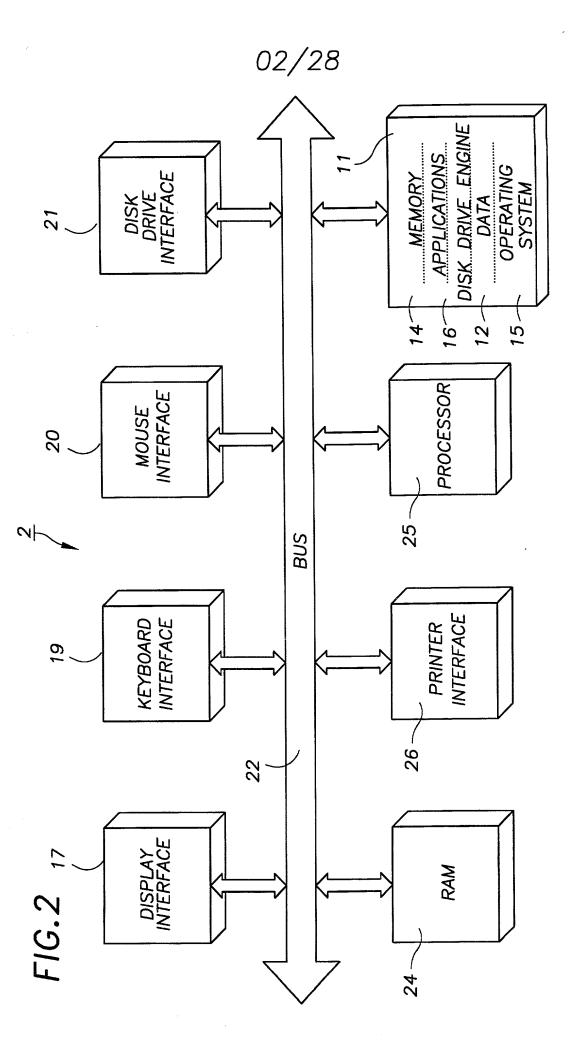
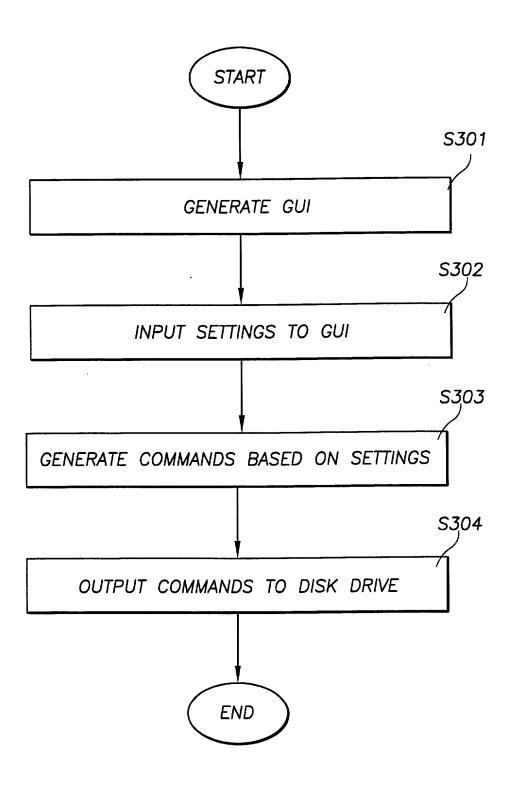
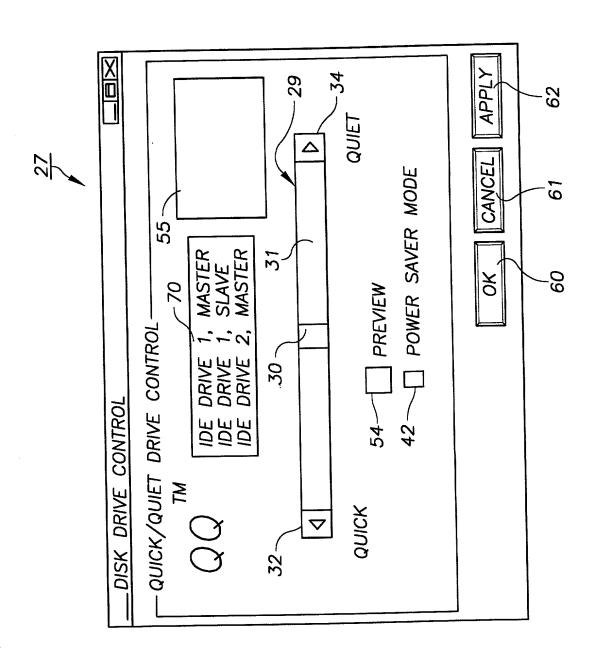
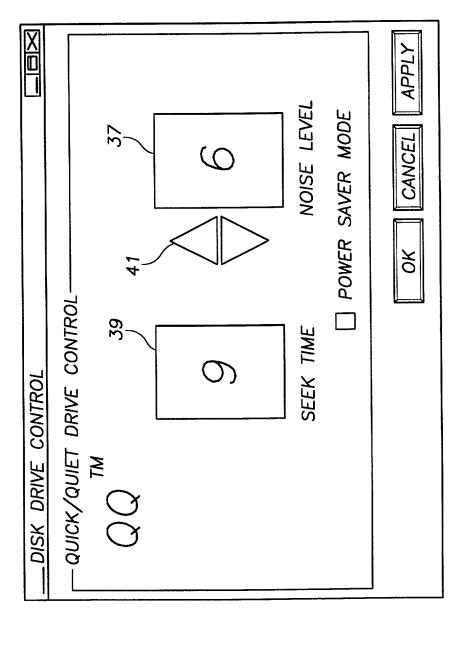


FIG.3



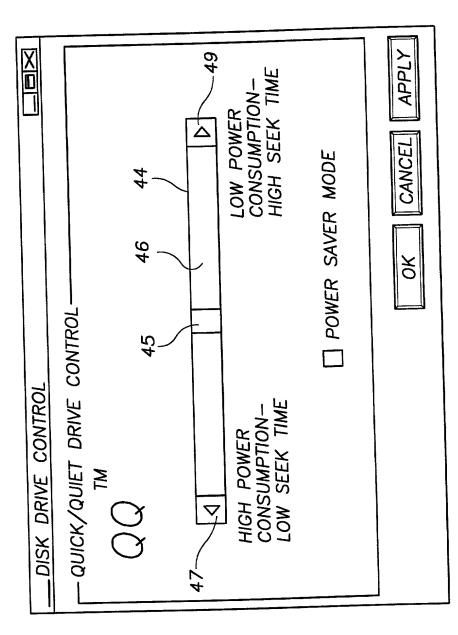






F1G.5





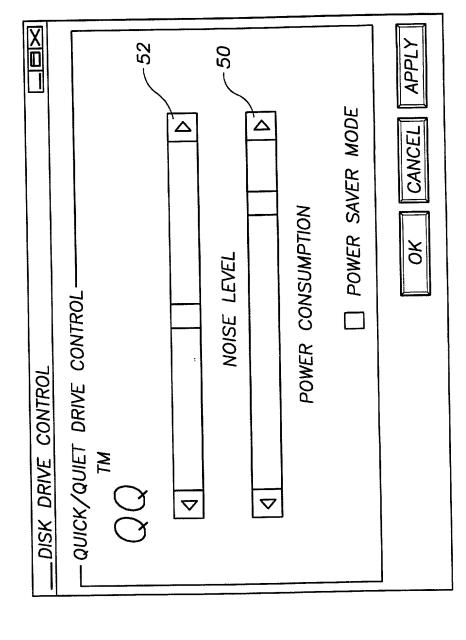
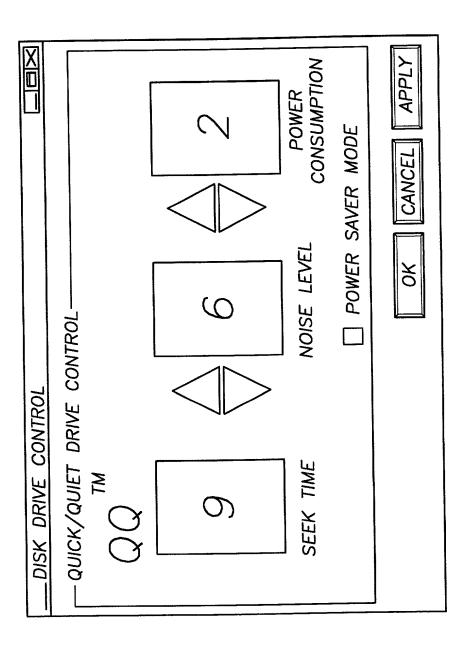


FIG.7



F1G.8

F1G.9

IDE DRIVE 1, MASTER

IDE DRIVE 1, SLAVE

IDE DRIVE 2, MASTER

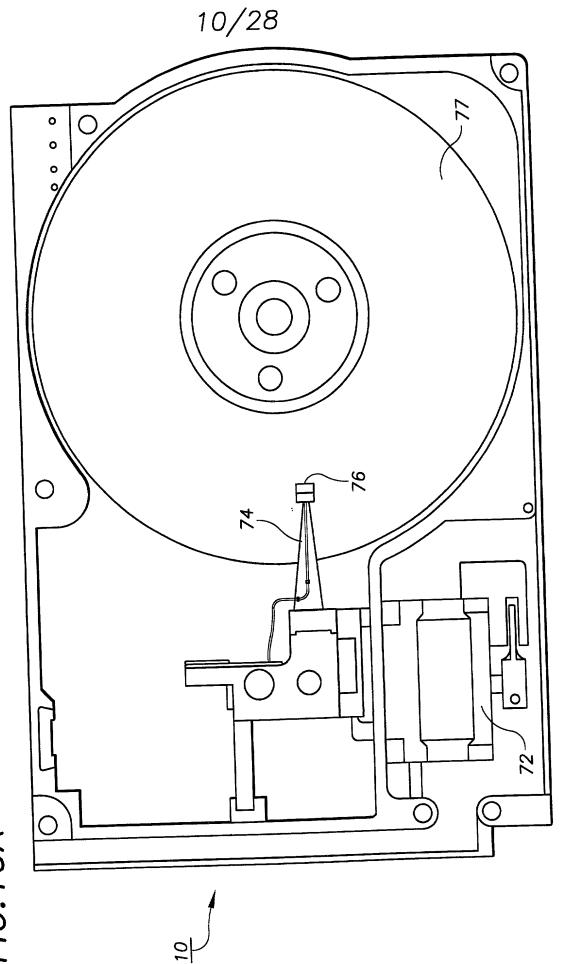


FIG. 10A

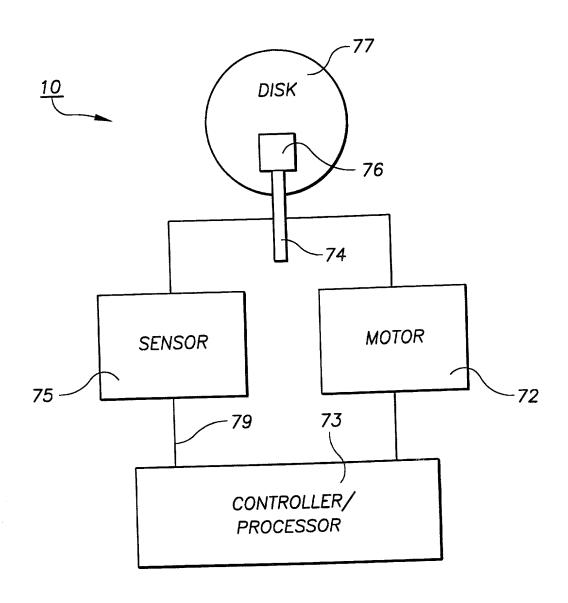
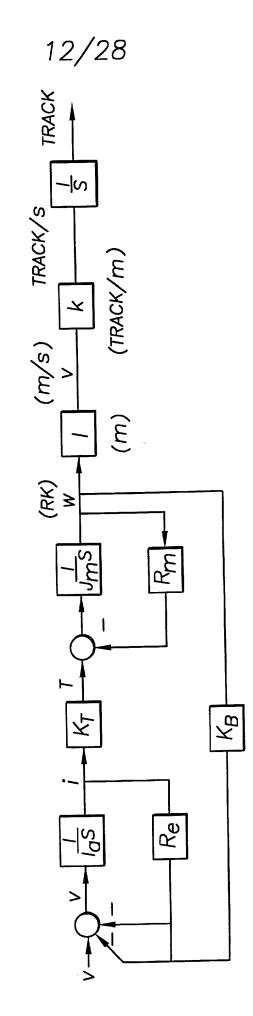


FIG. 11



BAD

-81

0

-5

0

2

MOVE DISTANCE (TRACKS)

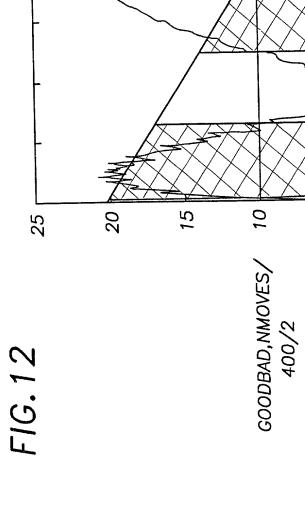


FIG. 13

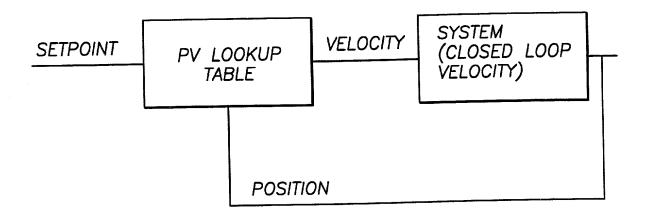


FIG. 14

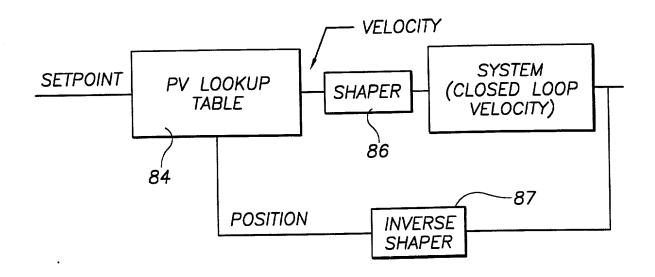


FIG. 15

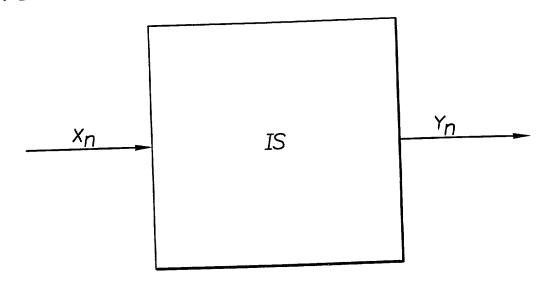


FIG. 16

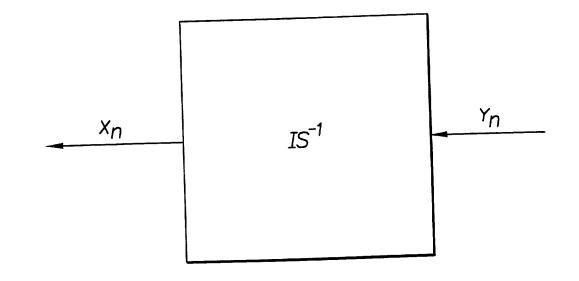


FIG. 17

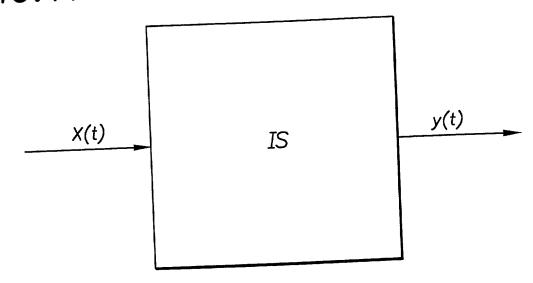
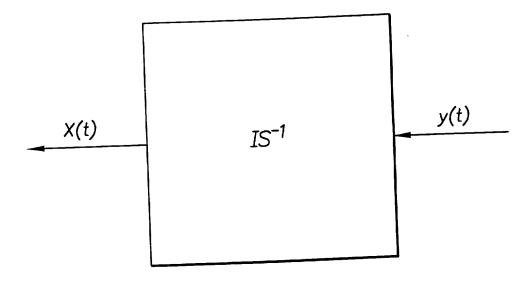


FIG18



The first that that the first team is the first team that the first team of the firs

FIG.19

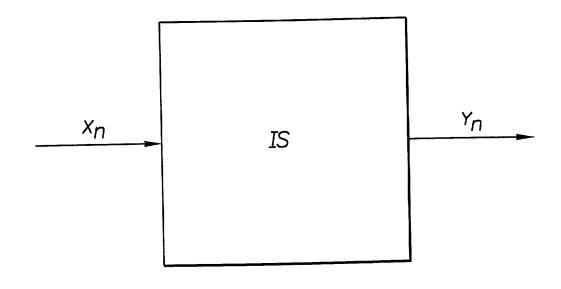
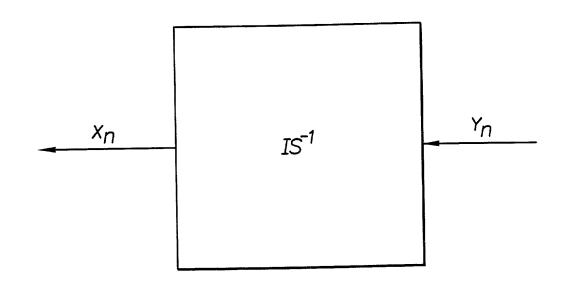
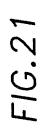
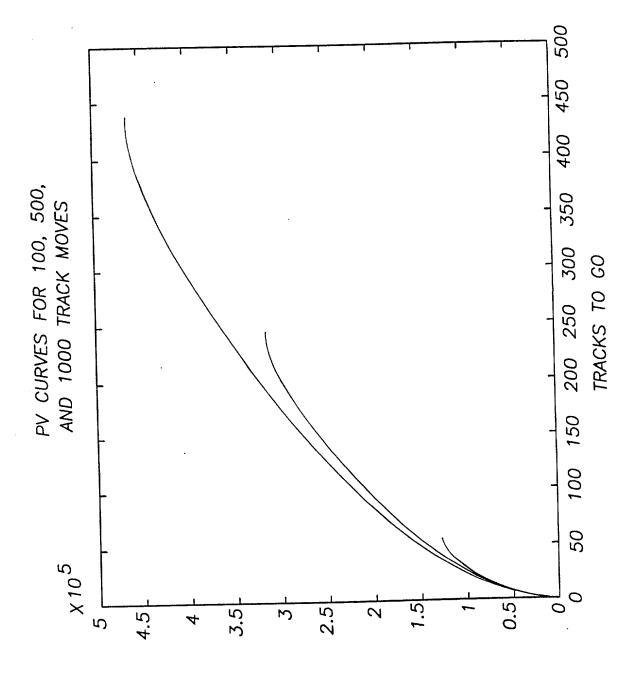


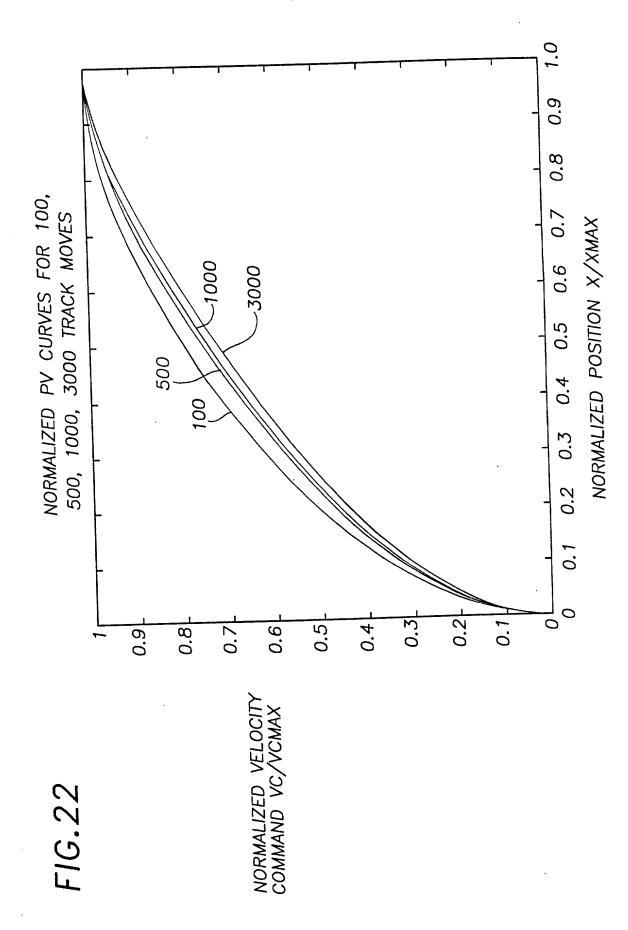
FIG20



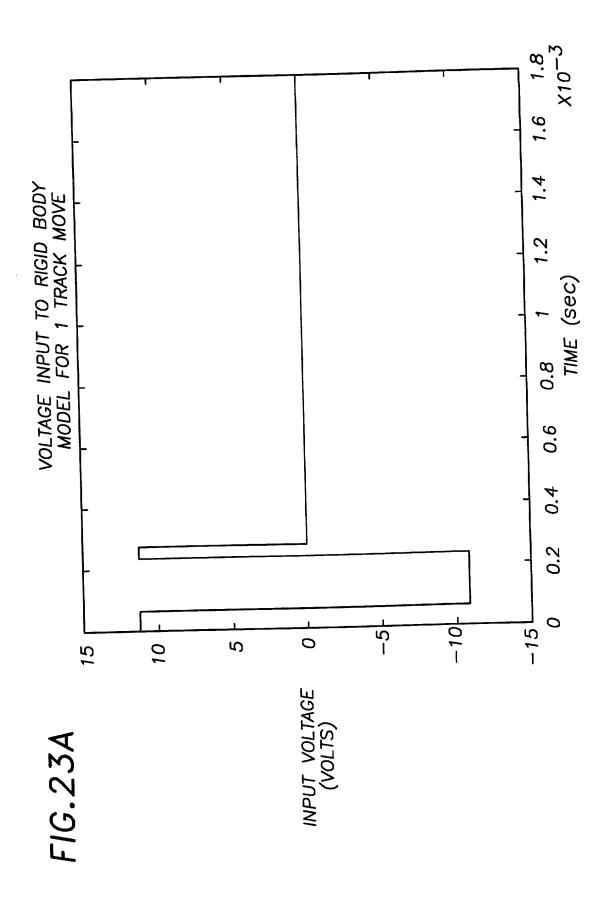




VELOCITY COMMAND (TRACKS/SEC)







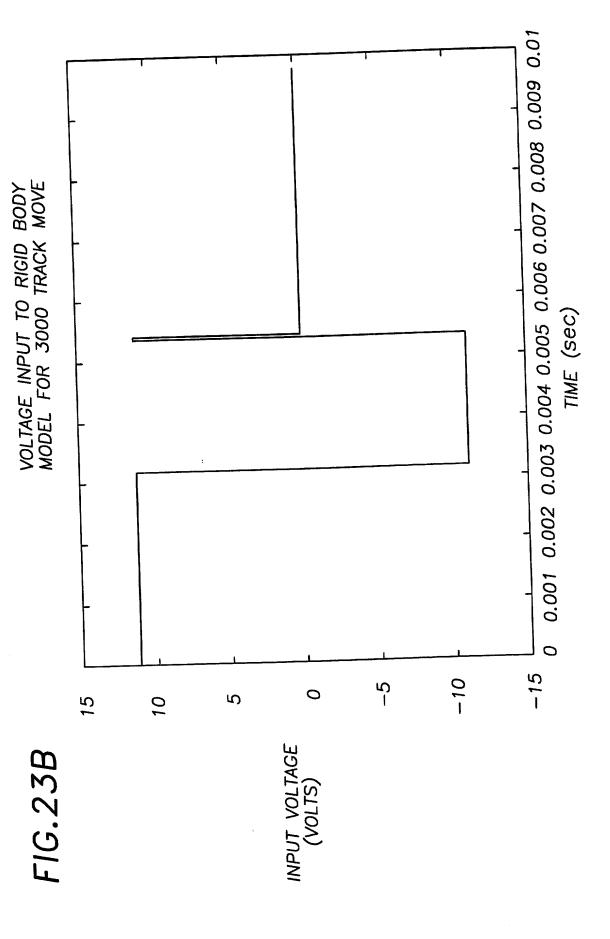


FIG.24

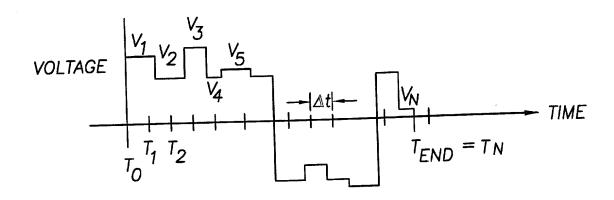


FIG.25

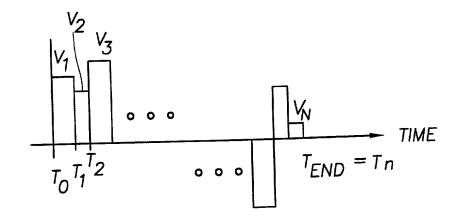


FIG.26

$$\begin{array}{c|c} V_1 & V_2 & V_N \\ \hline \hline T_1 & T_2 & + \circ \circ \circ + & \hline T_{END} \\ \hline T_0 & -V_1 & -V_2 & -V_N \\ \hline \end{array}$$

FIG.28

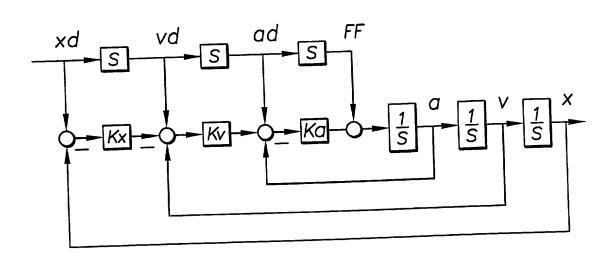


FIG.30

**一〇一型一〇** s3 KXKVKa s<sup>2</sup> KXKV XQ FIG. 29

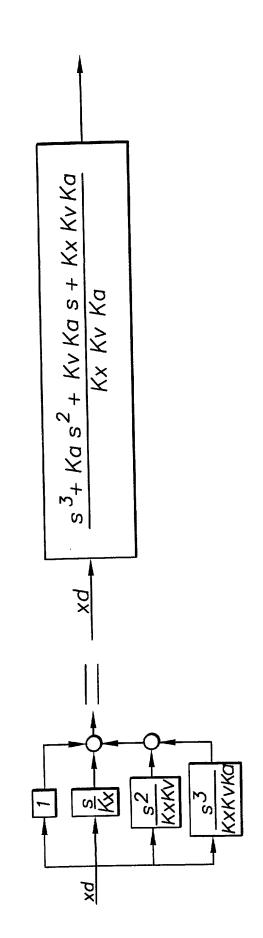


FIG.31

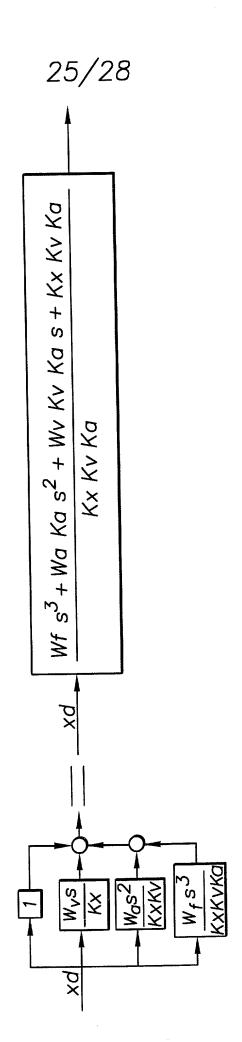
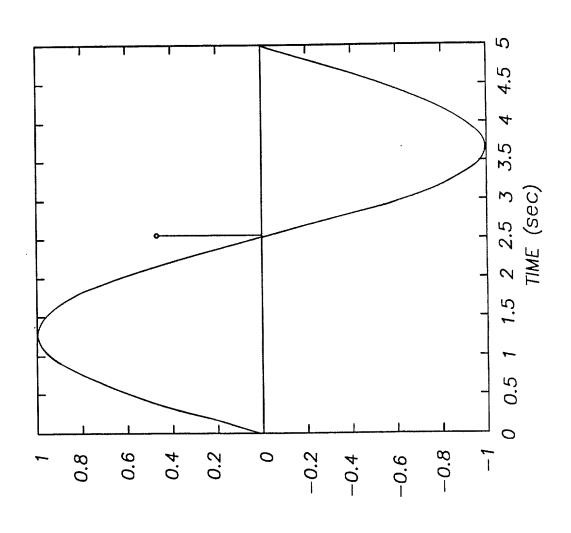


FIG.32



**AMPLITUDE** 

FIG.33

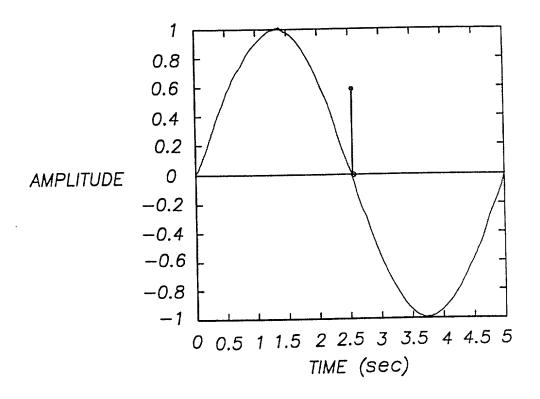


FIG.34

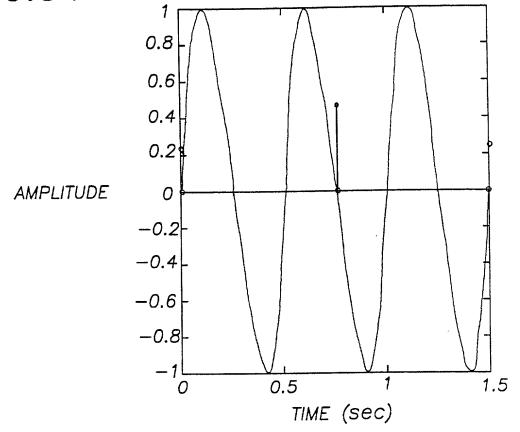


FIG.35

